

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	0	"73"/117.3 and (sensor with moving) and (scale with moving) and (measur\$6 with phase) and (map with geometric with path)	US-PGPUB	OR	ON	2005/10/28 20:55
L2	0	"73"/117.3 and (sensor with moving) and (scale with moving) and (measur\$6 with phase) and (map with geometric with path)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 20:56
L3	0	"73"/117.3 and (sensor with moving) and (scale with moving) and (measur\$6 with phase) and (control\$4 with camshaft)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 21:02
L5	1	sensor and scale and (measur\$6 with phase) and (control\$4 with camshaft) and ((sens\$3 detect\$3) with path with event)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 21:05
L6	1	sensor and scale and (measur\$6 with phase) and (control\$4 with camshaft) and (detect\$3 with path)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 21:04
L7	4	sensor and scale and (measur\$6 with phase) and ((sens\$3 detect\$3) with path with event) and (map with geographical)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 21:06
L8	1	7 and ((learn learning) with phase)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 21:07
L9	1	7 and ((learn learning) with phase)	US-PGPUB	OR	ON	2005/10/28 21:07
S1	4	("6283075" "6289862").pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 18:08

S4	1	(sensor with scale with moving) and (measur\$6 with phase) and (measur\$6 with path)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 19:04
S5	1	10/804590	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 18:42
S6	5	(sensor with moving) and (scale with moving) and (measur\$6 with phase) and (measur\$6 with path)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 18:59
S7	0	(control with camshaft) and (sensor with moving) and (scale with moving) and (measur\$6 with phase) and (measur\$6 with path)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 19:00
S8	1	(control\$4 with camshaft) and (sensor with moving) and (scale with moving) and (measur\$6 with phase) and (measur\$6 with path)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 19:00
S9	4	("6283075" "6289862").pn.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 19:03
S11	0	S9 and (learn\$3 with phase)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 19:03
S12	13	(sensor with moving) and (scale with moving) and (measur\$6 with phase) and (line with scale)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 16:25

S13	1	S12 and (geographical with interval)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 19:07
S14	1	S12 and (learn\$3 with phase)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 19:08
S15	0	("702"/\$.ccls. "123"/\$.ccls.) and (sensor with moving) and (scale with moving) and (measur\$6 with phase) and (geographical with interval)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 19:12
S16	1	("702"/\$.ccls. "123"/\$.ccls. "701"/\$.ccls.) and (sensor with moving) and (scale with moving) and (measur\$6 with phase) and (geographical with interval)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/24 19:12
S17	1	(sensor with moving) and (scale with moving) and (measur\$6 with phase) and (digital with signal with camshaft)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 17:01
S18	1	(sensor with moving) and (scale with moving) and (measur\$6 with phase) and ((learn learning) with phase) and (sensor same scale same (map with geographical with interval)) and ((sequent subsequent) same ((learn learning) with phase))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 17:05
S19	1	(sensor with moving) and (scale with moving) and (measur\$6 with phase) and ((learn learning) with phase) and (sensor same scale same (map with geographical with interval)) and ((sequent subsequent) same ((learn learning) with phase))	US-PGPUB	OR	ON	2005/10/28 17:08

S20	1	("702"/\$.ccls. "123"/\$.ccls. "701"/\$.ccls. "73"/\$.ccls.) and (sensor with moving) and (scale with moving) and (measur\$6 with phase) and ((learn learning) with phase) and (sensor same scale same (map with geographical with interval)) and ((sequent subsequent) same ((learn learning) with phase))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 17:08
S21	1	("702"/\$.ccls. "123"/\$.ccls. "701"/\$.ccls. "73"/\$.ccls.) and (sensor with moving) and (scale with moving) and (measur\$6 with phase) and ((learn learning) with phase) and (sensor same scale same (map with geographical with interval)) and ((sequent subsequent) same ((learn learning) with phase))	US-PGPUB	OR	ON	2005/10/28 20:54
S22	1	((sensor with moving) and (scale with moving) and (measur\$6 with phase) and ((learn learning) with phase) and (sensor same scale same (map with geographical with interval)) and ((sequent subsequent) same ((learn learning) with phase))).clm.	US-PGPUB	OR	ON	2005/10/28 17:08
S24	0	(digital with control) and (measur\$6 with phase) and (wheel with position with camshaft) and (rotation with information) and (angle with information) and (map with (geometric geogrphic\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 18:13
S25	0	(digital with control) and (measur\$6 with phase) and (wheel with position with camshaft) and (rotation with information) and (angle with information) and (map with (geometric geographic\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 18:14
S26	0	(digital with control) and (measur\$6 with phase) and (wheel with position\$3 with camshaft) and (rotation with information) and (angular with information) and (map with (geometric geographic\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 18:15

S27	0	(digital with control) and (measur\$6 with phase) and (wheel with position\$3) and camshaft and (rotation with information) and (angular with information) and (interval with (geometric geographic\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 18:16
S28	0	(measur\$6 with phase) and (wheel with position\$3) and camshaft and (rotation with information) and (angular with information) and (interval with (geometric geographic\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 18:17
S29	1	(measur\$6 with phase) and (wheel with position\$3) and camshaft and (rotation with information) and (angle with information) and (interval with (geometric geographic\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/10/28 18:17